

東北大天文学専攻H20年、物理問題[4]

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[1] 角運動量演算子の z 成分

$$L_z = xp_y - yp_x = i\hbar x \frac{\partial}{\partial y} - i\hbar y \frac{\partial}{\partial x} \quad (1)$$

を極座標で表現する。

$$r^2 = x^2 + y^2 + z^2 \implies \frac{\partial r}{\partial x} = \frac{x}{r}, \quad \frac{\partial r}{\partial y} = \frac{y}{r} \quad (2)$$

$$\tan^2 \theta = \frac{x^2 + y^2}{z^2} \implies \frac{\partial \theta}{\partial x} = \frac{\cos^3 \theta}{\sin \theta} \frac{x}{z^2}, \quad \frac{\partial \theta}{\partial y} = \frac{\cos^3 \theta}{\sin \theta} \frac{y}{z^2} \quad (3)$$

$$\tan \varphi = \frac{x}{y} \implies \frac{\partial \varphi}{\partial x} = -\frac{y}{x^2} \cos^2 \varphi, \quad \frac{\partial \varphi}{\partial y} = \frac{1}{x} \cos^2 \varphi \quad (4)$$

$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial \varphi}{\partial x} \frac{\partial}{\partial \varphi} = \frac{x}{r} \frac{\partial}{\partial r} + \frac{\cos^3 \theta}{\sin \theta} \frac{x}{z^2} \frac{\partial}{\partial \theta} - \frac{y}{x^2} \cos^2 \varphi \frac{\partial}{\partial \varphi} \quad (5)$$

$$\frac{\partial}{\partial y} = \frac{\partial r}{\partial y} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial y} \frac{\partial}{\partial \theta} + \frac{\partial \varphi}{\partial y} \frac{\partial}{\partial \varphi} = \frac{y}{r} \frac{\partial}{\partial r} + \frac{\cos^3 \theta}{\sin \theta} \frac{y}{z^2} \frac{\partial}{\partial \theta} + \frac{1}{x} \cos^2 \varphi \frac{\partial}{\partial \varphi} \quad (6)$$

$$\therefore (1), (5), (6) \implies L_z = i\hbar \cos^2 \varphi \frac{\partial}{\partial \varphi} + i\hbar \frac{y^2}{x^2} \cos^2 \varphi \frac{\partial}{\partial \varphi} = i\hbar \frac{\partial}{\partial \varphi} \quad (7)$$

[2] \hat{H} , $\hat{\mathbf{L}}^2$, \hat{L}_z の交換関係

$$[\hat{H}, \hat{\mathbf{L}}^2] = -\frac{\hbar^2}{2m} \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right), \hat{\mathbf{L}}^2 \right] + \frac{1}{2m} \left[\frac{\hat{\mathbf{L}}^2}{r^2}, \hat{\mathbf{L}}^2 \right] + [V(r), \hat{\mathbf{L}}^2] = -\frac{\hbar^2}{2m} \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right), \hat{\mathbf{L}}^2 \right] + [V(r), \hat{\mathbf{L}}^2] \quad (8)$$

$\hat{\mathbf{L}}^2$ は θ, φ に関する微分演算子より

$$\left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right), \hat{\mathbf{L}}^2 \right] = 0, \quad [V(r), \hat{\mathbf{L}}^2] = 0 \quad (9)$$

$$\therefore [\hat{H}, \hat{\mathbf{L}}^2] = 0 \quad (10)$$

$$[\hat{\mathbf{L}}^2, \hat{L}_z] = -\hbar^2 \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right), -i\hbar \frac{\partial}{\partial \varphi} \right] - \hbar^2 \left[\frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2}, -i\hbar \frac{\partial}{\partial \varphi} \right] = 0 \quad (11)$$

$$[\hat{H}, \hat{L}_z] = -\frac{\hbar^2}{2m} \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right), \hat{L}_z \right] + \frac{1}{2m} \underbrace{\left[\frac{\hat{\mathbf{L}}^2}{r^2}, \hat{L}_z \right]}_{(11)} + [V(r), \hat{L}_z] = 0 \quad (12)$$

これらの交換関係より $\hat{\mathbf{L}}^2, \hat{L}_z$ は観測量である。かつ (11) より同時観測が可能な量である。

[3] 動径方向のシュレディンガー方程式

$\hat{\mathbf{L}}^2 Y_{\ell m}(\theta, \varphi) = \ell(\ell+1)\hbar^2 Y_{\ell m}(\theta, \varphi)$ のとき、 $\Psi = R_\ell(r)Y_{\ell m}(\theta, \varphi)$ と書くと

$$\begin{aligned} H\Psi &= -\frac{\hbar^2}{2m} Y_{\ell m} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR_\ell}{dr} \right) + \frac{R_\ell}{2mr^2} \hat{\mathbf{L}}^2 Y_{\ell m} + V(r) R_\ell Y_{\ell m} \\ &= -\frac{\hbar^2}{2m} Y_{\ell m} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR_\ell}{dr} \right) + \frac{R_\ell}{2mr^2} \hbar^2 \ell(\ell+1) Y_{\ell m} + V(r) R_\ell Y_{\ell m} = E R_\ell Y_{\ell m} \end{aligned} \quad (13)$$

両辺を $-\hbar^2/2m Y_{\ell m}$ で割ると

$$\frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR_\ell}{dr} \right) - \frac{\ell(\ell+1)}{r^2} R_\ell + \frac{2m}{\hbar^2} (E - V(r)) R_\ell = 0 \quad (14)$$

[4] 動径成分の直交性

$$\begin{aligned} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR_{E\ell}}{dr} \right) - \frac{\ell(\ell+1)}{r^2} R_{E\ell} + \frac{2m}{\hbar^2} (E - V(r)) R_{E\ell} &= 0 \\ \implies R_{E'\ell} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR_{E\ell}}{dr} \right) - \frac{\ell(\ell+1)}{r^2} R_{E'\ell} R_{E\ell} + \frac{2m}{\hbar^2} (E - V(r)) R_{E'\ell} R_{E\ell} &= 0 \end{aligned} \quad (15)$$

$$\begin{aligned} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR_{E'\ell}}{dr} \right) - \frac{\ell(\ell+1)}{r^2} R_{E'\ell} + \frac{2m}{\hbar^2} (E' - V(r)) R_{E'\ell} &= 0 \\ \implies R_{E\ell} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR_{E'\ell}}{dr} \right) - \frac{\ell(\ell+1)}{r^2} R_{E\ell} R_{E'\ell} + \frac{2m}{\hbar^2} (E' - V(r)) R_{E\ell} R_{E'\ell} &= 0 \end{aligned} \quad (16)$$

$r^2\{(15) - (16)\}$ より

$$R_{E'\ell} \frac{d}{dr} \left(r^2 \frac{dR_{E\ell}}{dr} \right) - R_{E\ell} \frac{d}{dr} \left(r^2 \frac{dR_{E'\ell}}{dr} \right) + \frac{2m}{\hbar^2} (E - E') r^2 R_{E\ell} R_{E'\ell} = 0 \quad (17)$$

両辺を r , 区間 $[0, \infty]$ で積分することを考える。条件より

$$\int_0^\infty R_{E'\ell} \frac{d}{dr} \left(r^2 \frac{dR_{E\ell}}{dr} \right) dr = \left[r^2 R_{E'\ell} \frac{dR_{E\ell}}{dr} \right]_0^\infty - \int_0^\infty r^2 \frac{dR_{E'\ell}}{dr} \frac{dR_{E\ell}}{dr} dr = - \int_0^\infty r^2 \frac{dR_{E'\ell}}{dr} \frac{dR_{E\ell}}{dr} dr \quad (18)$$

$$\int_0^\infty R_{E\ell} \frac{d}{dr} \left(r^2 \frac{dR_{E'\ell}}{dr} \right) dr = \left[r^2 R_{E\ell} \frac{dR_{E'\ell}}{dr} \right]_0^\infty - \int_0^\infty r^2 \frac{dR_{E\ell}}{dr} \frac{dR_{E'\ell}}{dr} dr = - \int_0^\infty r^2 \frac{dR_{E\ell}}{dr} \frac{dR_{E'\ell}}{dr} dr \quad (19)$$

より

$$\frac{2m}{\hbar^2}(E - E') \int_0^\infty r^2 R_{E\ell} R_{E'\ell} dr = 0 \implies \therefore \int_0^\infty r^2 R_{E\ell} R_{E'\ell} dr = 0 \quad (E \neq E') \quad (20)$$

が成立する。

[5] シュレディンガー方程式の動径成分の性質
